

# Lightweight Lateral Inhibition Network for Single MR Image Super-Resolution

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### Contributions

 A lateral inhibition network (LIN) is proposed for single MR image SR. With a small amount of parameters and computational overhead, LIN can achieve accurate and fast SR reconstruction.
 We conduct a inhibition unit (LIU) to impose inhibitory regulation on features explicitly, which is motivated by the lateral inhibition mechanism.
 We propose to fuse the shallow features with different receptive field sizes, which increases the diversity of the extracted features and provide more effective evidence for nonlinear inference

# **Network Architecture**

The network architecture is shown in the following figure. Feature extraction is composed of a set of parallel dilated  $3\times3$  conv layers followed by a  $1\times1$  conv and a  $3\times3$  conv layer. The outputs of these dilation convolutions are concatenated together along the channel direction. The extracted shallow feature is fed into the nonlinear mapping part of the network, which consists of a series of cascaded lateral inhibition blocks (LIBs). Here, residual learning is adopted to stabilize model training. Image reconstruction includes a upscale module, which is usually followed by a  $3\times3$  conv layer.



and image reconstruction.

4. We experimentally verify that combining the lateral inhibition mechanism with the proposed shallow feature extraction strategy contributes to improving the performance of deep models.

## **Explicit Visual Inhibition**

A famous computing model for simulating visual inhibition is the Hartline-Ratliff Equation [1].

$$\hat{v}_i = \phi \left( v_i - \sum_{j \neq i} w_{ij} \cdot \max(0, v_j - t_{ij}) \right), \quad (1)$$

where  $\hat{v}_i$  denotes the *i*-th element of the reversed feature map  $\hat{\mathbf{v}}$ , and  $v_i$  is the *i*-th element of input feature  $\mathbf{v}$ .  $w_{ij}$  indicates the inhibition coefficient of the *j*-th neuron on the *i*-th neuron, while  $t_{ij}$ denotes the threshold that the *j*-th neuron must reach to inhibit the *i*-th neuron.  $\phi(\cdot)$  is a linear correction function, which we add to the original Hartline-Ratliff Equation. The symbols, i.e.,  $\otimes$  The overall network structure: The overall architecture of our LIN network. The dilated  $3 \times 3$  convolutions for feature extraction have different dilation rates to collect features in the receptive fields with different sizes.

# Ablation Investigation and Model Analysis

We keep the backbone of the network unchanged and adjust FE and IT accordingly. For FE, the comparative case is a single  $3 \times 3$  conv layer that is denoted as "0", and a group of dilated  $3 \times 3$  conv layers is denoted as "1". As for IT, "0" stands for removing the IT from a LIU, the opposite is denoted as "1". The valid curves of these different configurations are shown in the left figure. We also analysis the impact of the number of LIB and LIU on model performance. We fix n at 4 and set m = 2, 3, 4, and fix m at 4 and set n = 1, 2, 3, 4. The right figure shows the testing results of these configurations.



and  $\ominus$ , in the following figure are element-wise operations.



#### Inhibition tail (IT) of a lateral inhibition unit (LIU): The upper branch imitates the weight tensor

 $\mathbf{w}$  in the Hartline-Ratliff Equation, while the lower branch simulates the threshold tensor  $\mathbf{t}$ .

### References

[1] Hartline, H., Ratliff, F.: Studies on Excitation and Inhibition in the Retina. The Rockefeller University Press, New York, (1974) Alation study and model analysis: The valid curves of different configurations of the network for studying the feature extraction and visual inhibition mechanism (left). The testing performance comparison between the models with different numbers of LIB and LIU (right).

# Quantitative and Qualitative Evaluation

Quantitative comparison between typical SR models. The maximum values in each comparative cell are marked in red and the second ones are marked in blue (PSNR (dB) / SSIM).

		1						· ·			
	method	SR	param	bicubic downsampling				k-space truncation			
				PD PD		T1	Τ2	PD		<u>T1</u>	T2
	Bicubic	$\times 2$	/	35.04 / 0.	9664 33	$3.80 \ / \ 0.9525$	$33.44 \ / \ 0.9589$	34.65 / 0	.9625 33.38	/ 0.9460 (	$33.06 \ / \ 0.9541$
	NLM $[2]$	$\times 2$	/	37.26 / 0.	9773 35	$5.80 \ / \ 0.9685$	$35.58 \ / \ 0.9722$	36.18 / 0	.9707 34.71	/ 0.9581 (	$34.56 \ / \ 0.9641$
	SRCNN [3]	$\times 2$	$24.5\mathrm{K}$	38.96 / 0.	9836 37	$7.12 \ / \ 0.9761$	$37.32 \ / \ 0.9796$		.9802 36.52	/ 0.9705 3	$37.04 \ / \ 0.9773$
	VDSR [4]	$\times 2$	$0.67\mathrm{M}$	39.97 / 0.	9861 37	7.67 / 0.9783	$38.65 \ / \ 0.9836$		.9850 37.58	/ 0.9760 (	$38.74 \ / \ 0.9823$
	$\operatorname{RecNet}[5]$	$\times 2$	1.33M	40.43 / 0.	9873 37	7.86 / 0.9792	39.13 / 0.9848		.9857 37.54	/ 0.9764	39.03 / 0.9832
	FSCWRN [6]	$\times 2$	3.50M	40.72 / 0.	9880 37	7.98 / 0.9797	$39.44 \ / \ 0.9855$		.9876 38.04	/ 0.9786	39.82 / 0.9851
	LIN [Ours]	$\times 2$	1.33M	40.84 / 0.	9883 38	8.04 / 0.9798	39.50 / 0.9857		.9880 38.21	/ 0.9793	40.02 / 0.9855
	LIN+ [Ours]	$\times 2$	1.33M	41.03 / 0.	9886 38	8.19 / 0.9803	39.62 / 0.9860		.9886 38.40	/ 0.9801	$\frac{40.18}{0.9859}$
	Bicubic	$\times 3$	/	31.20 / 0.	9230 30	0.15 / 0.8900	29.80 / 0.9093		.9167 = 29.79	/ 0.8793	29.50 / 0.9016
	$\begin{bmatrix} NLM & [2] \\ CDCMN & [2] \end{bmatrix}$	X 3		$\begin{vmatrix} 32.81 \\ 22.60 \\ 0 \end{vmatrix}$	$9430 \qquad 31$	1.74 / 0.9216	31.28 / 0.9330	32.02 / 0	.9324 30.83	(0.9027)	30.57 / 0.9197
	SKONN [3] VDCD [4]	X 3	24.5K	33.60 / 0.	$9510 \qquad 32$	2.17 / 0.9276	32.20 / 0.9440	32.90 / 0	.9432 $31.72$	/ 0.9187	31.80 / 0.9381
	VDSR [4] DeeNet [5]	$\times 3$	0.07 M	34.00 / 0.	$\begin{array}{c c} 9599 & 5_{2} \\ 0652 & 2^{\prime} \end{array}$	2.91 / 0.9378	33.47 / 0.9009	34.27 / 0	$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$	(0.9304)	33.23 / 0.9515
	Recinet [5]		1.35 M	$\begin{vmatrix} 34.90 \\ 25.27 \\ 0 \end{vmatrix}$	9023 30 0653 30	5.03 / 0.9399	-33.83 / 0.9388 -34.97 / 0.0618		$ \begin{array}{c ccccccccccccccccccccccccccccccccccc$		33.09 / 0.9004
	$\frac{150 \text{ With } [0]}{\text{LIN } [\text{Ours}]}$	$\land$ $\lor$ $\land$	1.37M	35.37 / 0.	9055 50 9654 39	3.24 / 0.9423 3.23 / 0.9421	34.27 / 0.9018 34.26 / 0.9616		9030 $33.099642$ $33.25$		34.34 / 0.9003
	LIN + [Ours]	$\times 3$	1.37M	35.56 / 0.	9661 33	3.44 / 0.9440	$34.41 \ / \ 0.9627$	35.59 / 0	$9656 \qquad 33.50$	/ 0.9429	34.63 / 0.9622
	Bicubic	× 4	/	29.13 / 0	8799 28	8 28 / 0 8312	$\frac{31.11}{27.86}$ / 0.8611		8713 27.96	/ 0.8182	$\frac{31.00}{27.60}$ / 0.8511
	NLM [2]	$\times 4$	/	$\begin{vmatrix} 20.10 \\ 30.27 \\ 0 \end{vmatrix}$	9044 29	9.31 / 0.8655	28.85 / 0.8875		.8906 28.68	/ 0.8439	28.37 / 0.8718
	SRCNN [3]	$\times 4$	$24.5\mathrm{K}$	31.10 / 0.	9181 29	9.90 / 0.8796	29.69 / 0.9052	30.52 / 0	.9078 29.31	/ 0.8616	29.32 / 0.8960
	VDSR [4]	$\times 4$	$0.67\mathrm{M}$	32.09 / 0.	9311 30	$0.57 \ / \ 0.8932$	$30.79\ /\ 0.9240$	31.69 / 0	.9244 30.14	/ 0.8818	$30.51\ /\ 0.9162$
	RecNet [5]	$\times 4$	$1.33\mathrm{M}$	32.58 / 0.	.9378 30	0.86 / 0.9005	$31.30\ /\ 0.9310$	32.16 / 0	.9310 30.46	/ 0.8900	$31.03\ /\ 0.9243$
	FSCWRN [6]	$\times 4$	$3.50\mathrm{M}$	32.91 / 0.	9415 30	0.96 / 0.9022	$31.71\ /\ 0.9359$	32.78 / 0	.9387 30.79	/ 0.8973	$31.71\ /\ 0.9334$
	LIN [Ours]	$\times 4$	$1.36\mathrm{M}$	32.94 / 0.	9417 31	1.01 / 0.9033	$31.72 \ / \ 0.9361$	32.82 / 0	.9391 30.88	/ 0.8990	$31.77 \ / \ 0.9339$
	LIN+ [Ours]	$\times 4$	$1.36\mathrm{M}$	33.12 / 0.	.9432 31	$1.28 \ / \ 0.9073$	$31.88 \ / \ 0.9376$	33.03 / 0	.9415 31.20	/ 0.9041	$31.96 \ / \ 0.9362$
	Picubic	NII M	CD		VIDED		PacNat	FSCWDN	I IN [Ours]		Ground Truth
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	As can be seen from both quantitative and visual						achieve better SK performance with fewer model				
	comparisons	s abo	ve, the	proposed	d LIN n	nodel can	parameter	rs and co	mputation	al overhe	ead.
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